

**Academic year 2024/2025**

**Courses offered by the programme**

## **Génie Mécanique et Automatique (GMA) Mechanical and Control Systems Engineering**

**Semester(s) :**

Curricula are organized in groups of courses (Unités d'Enseignement (UE)), consisting of several courses (Eléments Constitutifs (EC)). An EC is a teaching module including lectures (cours magistraux (CM)), tutorials (travaux dirigés (TD)), laboratory work (travaux pratiques (TP)), projects (PR), conferences (CONF), personal work (TA) and possibly other pedagogical activities (DIV). Some internships (stages (ST)) are compulsory

### **Commonly used abbreviations**

**CM : Lectures  
TD : Tutorials  
TP : Laboratory Work  
CONF : Conferences  
TA : Personal Work  
PR : Project  
ST : Internship  
DIV : Miscellaneous**

|                                              |                         |
|----------------------------------------------|-------------------------|
| <b>Automation III: Optimal Control</b>       | <b>GMA09-COMOP</b>      |
| <b>Number of hours : 24.00 h</b>             | <b>2.00 ECTS credit</b> |
| <b>Reference Teacher(s) : GUEGAN Sylvain</b> |                         |

**Objectives :**

Problems associated with optimal control of dynamic systems, including a number of practical problems: Control with minimal expenditure of energy, Control in minimal time, etc. Study of linear quadratic commands. Introduction of robustness of the Gaussian linear quadratic commands;  $H_2$  and  $H_\infty$

**Content :**

Mathematics in optimal control. Calculation of variations. Principle of the maximum. Dynamic programming. Optimal control of linear systems. Additions from Lyapunov's theory. Quadratic optimisation of continuous systems. Continuous stationary regulator. Quadratic optimisation of discrete systems. Discrete stationary regulator. Linear quadratic command system + stability. Gaussian linear quadratic commands  $H_2$  et  $H_\infty$

**Bibliography :**

KWAKERNAAK H. SIVAN R., 1972, « Linear optimal control systems», John Wiley 1 Sons, Inc.  
 THOMAS Y., 1992 « Signaux et systèmes linéaires » 1991, Masson  
 DE LARMINAT Ph. 1993, « Automatique, commande des systèmes linéaires », Hermès.

**Requirements :**

Signaux et Systèmes - Automatique 1 - Automatique 2

**Organisation :**

Revision of lecture notes. Preparation of exercises, problems and practical work (Two hours per week).

**Evaluation :**

Three-hour written examination at the end of the semester(lecture notes and handouts allowed).  
 Two practical work reports .

**Target :**